

$l \quad i$

v_{ee}

v_{ei}

v_{ie}

v_{ii}

$O(1)$

$O\left(\sqrt{\frac{m_e}{m_i}}\right)$

$O\left(\frac{m_e}{m_i}\right)$

v_{ee}

v_{ei}

v_{ii}

v_{ie}

$l-l$

Just $e \quad e$ at rest
 $\bullet \longrightarrow \bullet$

Before the collision

$\bullet \bullet \longrightarrow$

after $= =$

$\Delta_{E_{ee}} \sim v_{ee}$

$\Delta_{E_{ii}} \sim v_{ii}$

Fast ion against e at rest

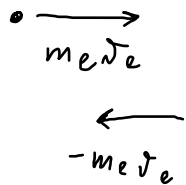
After the collision

$v_e = 2v_i$

$\Delta_{E_{ei}} \sim \frac{m_e}{m_i} v_{ei}$

$\frac{1}{2} m_e v_e^2 = \frac{1}{2} m_e 4 v_i^2$
 $= 4 \frac{m_e}{m_i} \left(\frac{1}{2} m_i v_i^2 \right)$

Fast electron against ion at rest



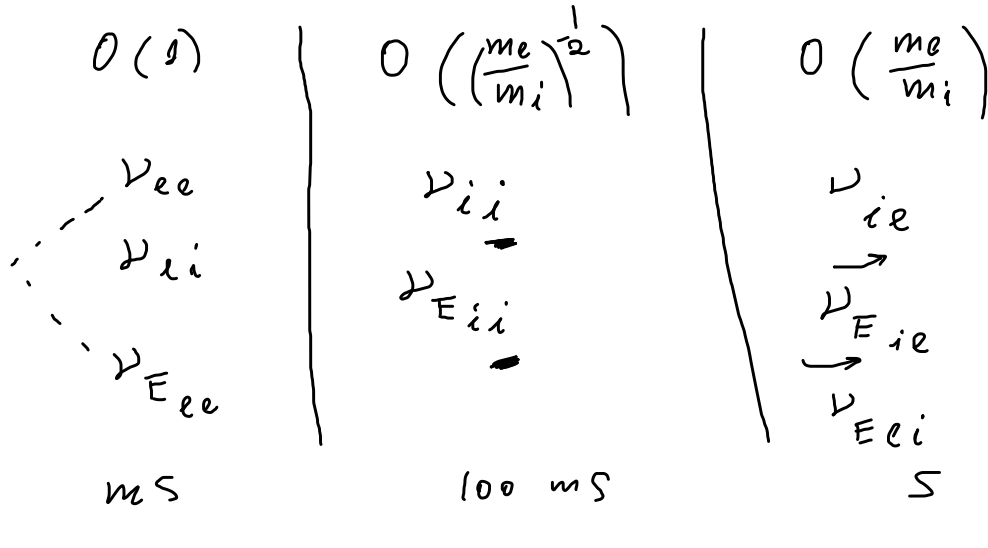
$$m_e v_e^i + m_i v_i^i = m_e v_e^f + m_i v_i^f$$

$$v_i^f = \frac{m_e (v_e^i - v_e^f)}{m_i}$$

$$v_i = \frac{2m_e v_e}{m_i}$$

$$\frac{1}{2} m_i v_i^2 = \frac{1}{2} m_i \frac{4 m_e^2 v_e^2}{m_i} = \frac{4 m_e}{m_i} \left(\frac{1}{2} m_e v_e^2 \right)$$

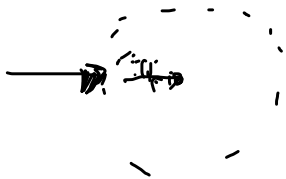
$$\mathcal{E}_{Ei} \sim \frac{m_e}{m_i} \cdot \mathcal{E}_{Ee}$$



eg.

Neutral beam injection

$T_i > T_e$



$$m \frac{dv}{dt} = qE - \overbrace{m\nu \dot{\sigma}}^{\text{friction due to collisions}}$$

E required to drive & warrant

Steady state: $\frac{dv}{dt} = 0$

$$v = \frac{qE}{m\nu}$$

$$\eta \propto \nu \propto T^{-\frac{1}{2}} \quad E = \eta \dot{\sigma} \quad \dot{\sigma}: \text{current density}$$

$$\nu \propto \nu_m \propto T^{-\frac{1}{2}}$$

$$\nu \propto \nu \propto \frac{1}{\sigma_m}$$

$$\dot{\sigma} = nq v = \frac{nq q E}{m\nu} = \left(\frac{nq^2}{m\nu} \right) E$$

$$\eta = \frac{m\nu}{nq^2}$$

$$\begin{aligned} \sigma &= n \cdot v \cdot \sigma^* \propto \frac{1}{\nu^3} \\ \sigma^* &= \frac{qTqF}{2\pi\epsilon_0 M^2 \nu^2} \end{aligned}$$

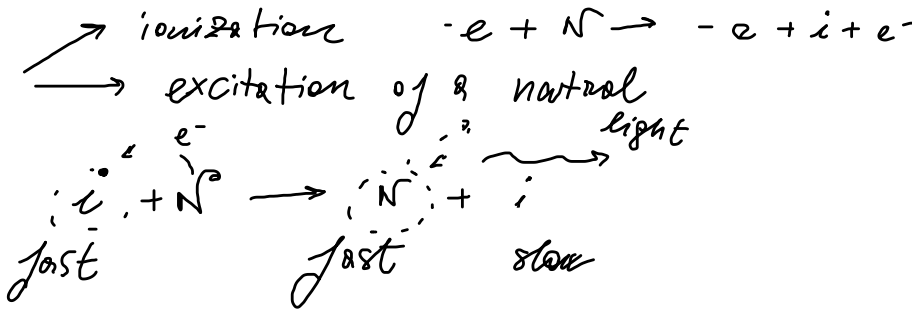
$$\sigma^* = \frac{qTqF}{2\pi\epsilon_0 M^2 \nu^2} \quad \text{but}$$

Collisions with neutrals

1) Elastic collision

2) Inelastic collisions

3) Charge exchange



$$\sigma \sim \pi a_0^2 \sim 10^{-20} \text{ m}^2$$

A

Charged particle motion in $\underline{E}(x,t)$ and $\underline{B}(x,t)$

$$m \frac{d\underline{v}}{dt} = q (\underline{v} \times \underline{B})$$

If \underline{B} is $\overrightarrow{\text{const}}$ or it is not

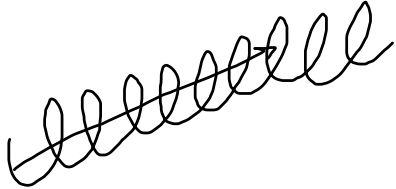
$$\underline{v} \cdot \left[m \frac{d\underline{v}}{dt} \right] = q (\underline{v} \times \underline{B}) \cdot \underline{v}$$

$$\frac{d}{dt} \left(\frac{1}{2} m v^2 \right) = 0 \Rightarrow \frac{1}{2} m v^2 = \text{const} \Rightarrow |\underline{v}| = \text{const}$$

$$\underline{B} = \underline{\text{const}}$$

{ along the field line: uniform straight motion
 $\underline{v}_{\parallel}$

{ in a plane \perp to the field line: circular motion

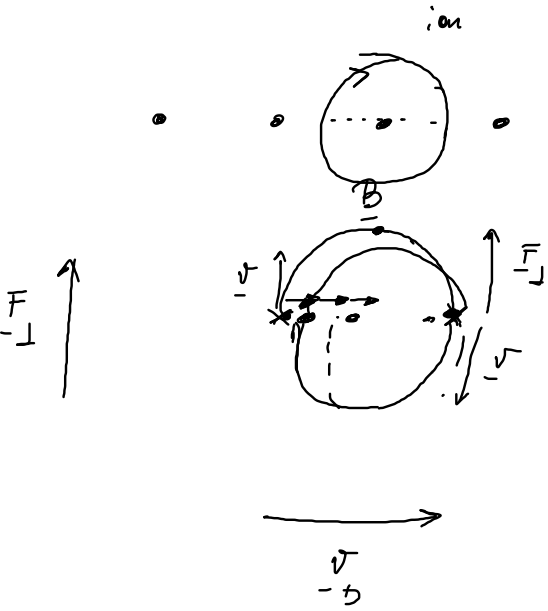


$$r_L = \frac{m v_{\perp}}{q B} \quad \omega_L = \frac{q B}{m}$$

\underline{B} + an external $\underline{F} = \underline{\text{const}}$

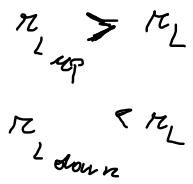
$$\underline{F} = \underline{F}_{\parallel} + \underline{F}_{\perp}$$

↳ accelerated straight motion along \underline{B}



$$F_{\perp} = 0$$

$$r_L = \frac{m \bar{v}_{\perp}}{qB}$$



$$m \frac{d\bar{v}}{dt} = q(\bar{v} \times \underline{B}) + \underline{F}$$

①

$$m \frac{d\bar{v}_{\parallel}}{dt} = F_{\parallel} \Rightarrow \bar{v}_{\parallel}(t) = \frac{F_{\parallel}}{m} t + \bar{v}_{\parallel}(0)$$

②

$$m \frac{d\bar{v}_{\perp}}{dt} = q(\bar{v}_{\perp} \times \underline{B}) + \underline{F}_{\perp}$$

Assume \vec{v} const

$$\vec{v} = \vec{v}_L + \vec{v}_D$$

$$\underbrace{m \frac{d\vec{v}_L}{dt}}_{\text{dormon motion}} + m \frac{d\vec{v}_D}{dt} = \underbrace{q \vec{v}_L \times \vec{B}}_{\text{dormon motion}} + q \vec{v}_D \times \vec{B} + \vec{F}_\perp$$

$$\vec{v}_D = \text{const}$$

$$\Rightarrow \frac{d\vec{v}_D}{dt} = 0$$

$$m \frac{d\vec{v}_D}{dt} = q (\vec{v}_D \times \vec{B}) + \vec{F}_\perp$$
$$0 = q (\vec{v}_D \times \vec{B}) + \vec{F}_\perp \times \vec{B}$$

$$0 = q (\underline{v} \times \underline{B}) \times \underline{B} + \underline{F}_{-1} \times \underline{B}$$

$$\underline{A} \times (\underline{B} \times \underline{C}) = (\underline{C} \times \underline{B}) \times \underline{A} = (\underline{A} \cdot \underline{C}) \underline{B} - (\underline{A} \cdot \underline{B}) \underline{C}$$

$$(\underline{v} \times \underline{B}) \times \underline{B} = \cancel{(\underline{v} \cdot \underline{B}) \underline{B}} - B^2 \underline{v} = -B^2 \underline{v}$$

$$0 = -qB^2 \underline{v} + \underline{F}_{-1} \times \underline{B} \Rightarrow \underline{v} = \frac{\underline{F}_{-1} \times \underline{B}}{qB^2}$$

$\bullet \underline{B}$
 $\xrightarrow{\underline{v}}$

$$\underline{F} = m \underline{a}$$

$$\underline{F}_{-1} = q \underline{E}_{-1}$$

\underline{v}_{-D_e} and \underline{v}_{-D_i} will be opposite
 $\underline{v}_{-D} = \frac{\underline{F}_{-1} \times \underline{B}}{B^2}$

\underline{F}_{-1}
 \uparrow