

(II)

$$m \frac{d\mathbf{v}_L}{dt} = q \left[ \mathbf{E} + \langle \mathbf{v}_L \times (\mathbf{v}_L \cdot \nabla) \mathbf{B} \rangle \right]$$

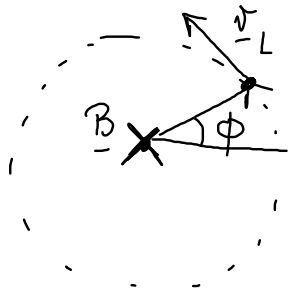
(I)

$$m \frac{d\mathbf{v}_\perp}{dt} = q \frac{\mathbf{v}_\perp}{c} \times \mathbf{B} + \mathbf{F}_\perp$$

$$\mathbf{F}_\perp = q \mathbf{E}_\perp + q \langle \mathbf{v}_\perp \times (\mathbf{v}_\perp \cdot \nabla) \mathbf{B} \rangle - m \frac{\mathbf{v}_\perp^2}{c} \frac{(\mathbf{v}_\perp \cdot \nabla) \mathbf{b}}{b}$$

$$\mathbf{v}_\perp^{(0)} = \frac{\mathbf{F}_\perp \times \mathbf{B}}{qB^2} \quad \mathbf{v}_\perp^{(1)} = \frac{m}{qB^2} \frac{d\mathbf{F}_\perp}{dt}$$

$$q \langle \underline{v}_L \times (\underline{n}_L \cdot \nabla) \underline{B} \rangle = ?$$



In  $\alpha = \alpha_{sc}$   $\underline{B} \neq -\hat{k}$   
 At the particle position  
 $\underline{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$

$$\underline{v}_L = \left[ -\sin(\omega_L t) \hat{i} + \cos(\omega_L t) \hat{j} \right] \frac{v_L}{\omega_L}$$

$$\underline{r}_L = \frac{v_L}{\omega_L} \left[ \cos(\omega_L t) \hat{i} + \sin(\omega_L t) \hat{j} \right]$$

$$\frac{v_L^2 q}{\omega_L} \left\langle \left( -\sin(\omega_L t) \hat{i} + \cos(\omega_L t) \hat{j} \right) \times \left( \cos(\omega_L t) \hat{i} + \sin(\omega_L t) \hat{j} \right) \cdot \left[ \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right] \left( B_x \hat{i} + B_y \hat{j} + B_z \hat{k} \right) \right\rangle$$

$$= \frac{qV_L^2}{\omega_L} \left\langle \left( -\sin(\omega_L t) \hat{k} + \cos(\omega_L t) \hat{d} \right) \cdot \left( \cos(\omega_L t) \left( \frac{\partial B_x}{\partial x} \hat{k} + \frac{\partial B_y}{\partial x} \hat{d} + \frac{\partial B_z}{\partial x} \hat{k} \right) + \sin(\omega_L t) \left( \frac{\partial B_x}{\partial y} \hat{k} + \frac{\partial B_y}{\partial y} \hat{d} + \frac{\partial B_z}{\partial y} \hat{k} \right) \right) \right\rangle$$

$$\begin{aligned} \langle \sin(\omega_L t) \rangle &= 0 \\ \langle \cos(\omega_L t) \rangle &= 0 \\ \langle \sin(\omega_L t) \cos(\omega_L t) \rangle &= 0 \end{aligned} \quad \left[ = \frac{qV_L^2}{2\omega_L} \left( \underbrace{-\frac{\partial B_x}{\partial x} \hat{k} + \frac{\partial B_z}{\partial x} \hat{k}}_{+\frac{\partial B_z}{\partial y} \hat{d}} + \frac{\partial B_z}{\partial y} \hat{d} - \underbrace{\frac{\partial B_y}{\partial y} \hat{k}} \right) \right]$$

$$\langle \sin^2(\omega_L t) \rangle = \langle \cos^2(\omega_L t) \rangle = \frac{1}{2}$$

$$= \frac{qV_L^2}{2\omega_L} \cdot \left( \frac{\partial B_z}{\partial x} \hat{k} + \frac{\partial B_z}{\partial y} \hat{d} + \frac{\partial B_z}{\partial z} \hat{k} \right) \Rightarrow \begin{aligned} \nabla \cdot \mathbf{B} = 0 &\Rightarrow \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z} = 0 \\ -\frac{\partial B_x}{\partial x} - \frac{\partial B_y}{\partial y} &= \frac{\partial B_z}{\partial z} \end{aligned}$$

$$= \frac{q v_L^2}{2 \omega_L} - \nabla |B| (r_{gc})$$

$$F = - \frac{q v_L^2}{2 \omega_L} \nabla |B| (r_{gc})$$

$$\frac{q v_L^2}{2 q B} m = \frac{m v_L^2}{2 B} = \frac{K_L}{B} = \text{magnetic moment} \mu$$



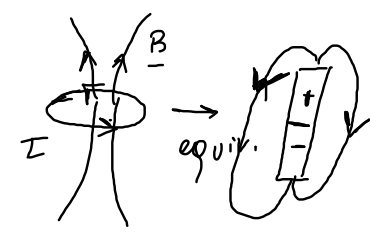
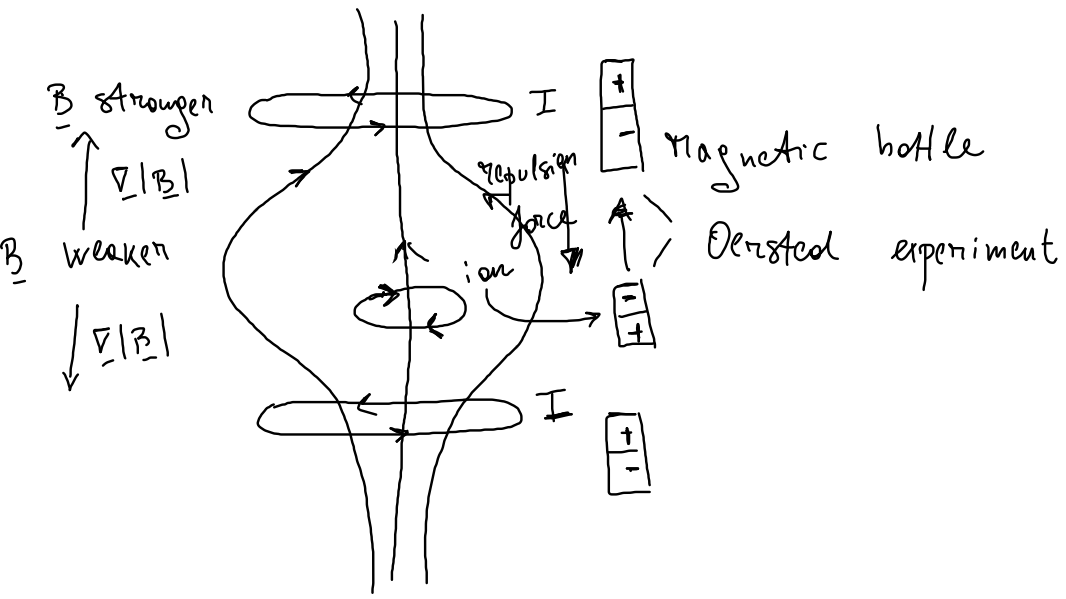
$$A = \pi \cdot r_L^2$$

$$W = \pi r_L^2 \frac{q}{T_L}$$

$$\underline{W = I \cdot A}$$

$$\mu = \frac{m v_L^2}{2 B}$$

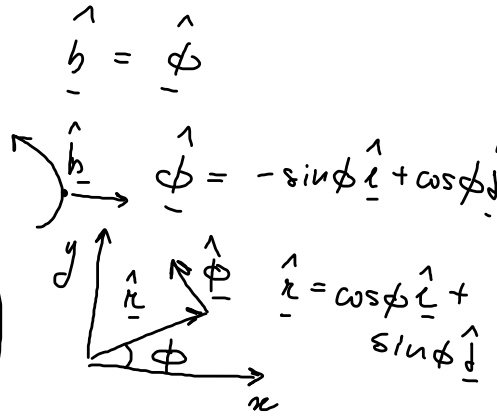
$$= \pi \frac{m^2 v_L^2}{2 B^2} \cdot \frac{q \cdot \omega_L}{2 \pi} = \frac{\pi m^2 v_L^2 q \omega_L}{2 B^2}$$



$$\underline{\underline{F}} = -m\underline{\underline{v}}^2 (\underline{\underline{b}} \cdot \underline{\underline{\nabla}}) \underline{\underline{b}}$$

$$\underline{\underline{F}} = -m\underline{\underline{v}}^2 \left( \frac{1}{r} \frac{\partial}{\partial \phi} \right) \begin{pmatrix} -\sin\phi \hat{r} \\ +\cos\phi \hat{\phi} \end{pmatrix} =$$

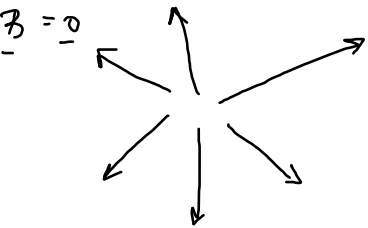
$$= -\frac{m\underline{\underline{v}}^2}{r} \left[ -\cos\phi \hat{r} - \sin\phi \hat{\phi} \right] = \frac{m\underline{\underline{v}}^2}{r} \hat{r}$$



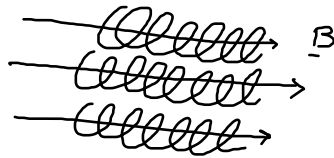
$$\underline{\underline{F}} = \underline{\underline{F}}_{\underline{\underline{E}}} + \underline{\underline{F}}_{\underline{\underline{\nabla|B|}}} + \underline{\underline{F}}_{\underline{\underline{centr.}}}$$

centrifugal force

# Consequence of drifts on magnetic confinement

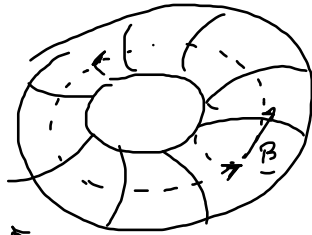


$\underline{B} \neq 0$



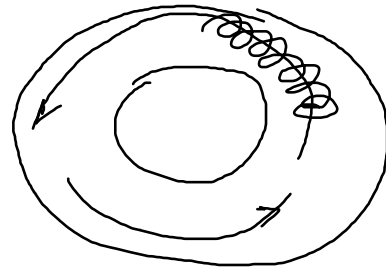
Close the field line

Linear system  $\rightarrow$  toroidal system

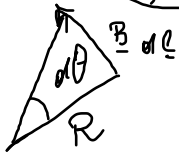


Ampere's law

$$\oint_C \underline{B} \cdot d\underline{l} = \mu_0 I_{\text{enclosed}}$$



$I_{\text{enclosed}} = I \cdot N$

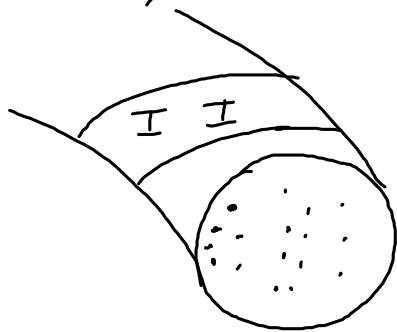


$\underline{B} \cdot d\underline{l} = BR d\theta$

$C \equiv$  circle of radius  $R$

$$\oint_C \underline{B} \cdot d\underline{l} = BR \int_0^{2\pi} d\theta = 2\pi BR$$

$$2\pi R B = \mu_0 N I \Rightarrow B(R) = \frac{\mu_0 N I}{2\pi R} \quad B \propto \frac{1}{R}$$



↑ ions  
↓ E  
↓ electrons

$$\underline{F} = -\mu \underline{\nabla} |\underline{B}|$$

$$\mu = \frac{m v_{\perp}^2}{2B}$$

$$\underline{v}_D = \frac{\underline{F} \times \underline{B}}{q B^2} = -\mu \frac{\underline{\nabla} |\underline{B}| \times \underline{B}}{q B^2}$$

←  
 $\underline{\nabla} |\underline{B}|$

$\underline{\nabla} |\underline{B}| \approx$  radial

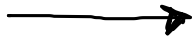
$\underline{B} \approx$  toroidal

$\Rightarrow \underline{\nabla} |\underline{B}| \times \underline{B} \approx$  vertical

$$\underline{v}_D = \frac{\underline{F} \times \underline{B}}{q B^2}$$

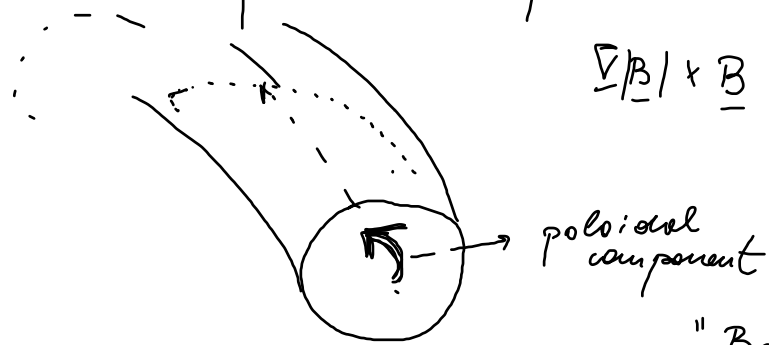
same direction for ions and electrons

$\underline{E}$  produced by charge separation





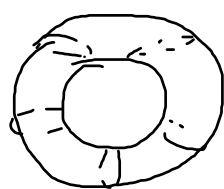
Add a poloidal component to  $\vec{B}$



$$\nabla |B| \times \underline{B}$$

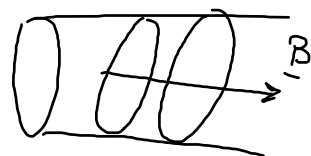
↑  
↓

$$\nabla |B|$$



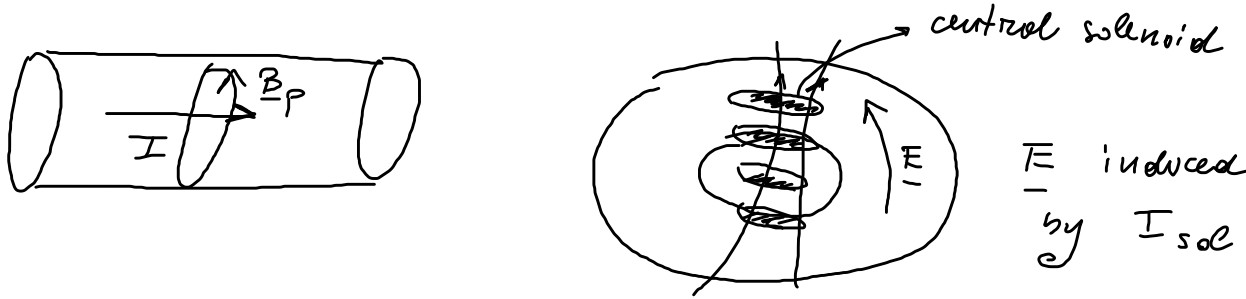
TORUS

"Bend the coil"  
Stellarator



Drawback:  
lose symmetry  
↓  
helps confinement

Tokamak approach: drive a toroidal current



Advantage: symmetry / simplicity

Disadvantage: transient system