

$\theta \ll 1$

$$\ddot{\theta} = -\omega^2(E) \theta$$

$$\omega^2(t) = \frac{g}{l(t)}$$

Se $l = \text{const}$

$$\theta = \operatorname{Re} \left[\theta_0 e^{i \int_0^t \omega dt'} \right] = \theta_0 \cos(\omega t)$$

Se $l = l(t)$ cerchiamo una soluzione

$$\theta(t) = \operatorname{Re} \left[\theta_0(t) e^{i \int_0^t w(t') dt'} \right]$$

Calcoliamo

$$\frac{d\theta}{dt} = \operatorname{Re} \left[\dot{\theta}_0 \exp \left[\dots \right] + \theta_0 \exp \left[\dots \right] \cdot i\omega(t) \right]$$

$$- \frac{\omega^2}{l}$$

$$\frac{d^2\theta}{dt^2} = \operatorname{Re} \left[\ddot{\theta}_0 \exp \left[\dots \right] + \dot{\theta}_0 \underbrace{i\omega \exp \left[\dots \right]}_{+ \theta_0 \exp \left[\dots \right] i\omega} + \theta_0 \underbrace{\exp \left[\dots \right] i\omega(t)}_{+ \theta_0 \exp \left[\dots \right] i\omega} + \theta_0 \exp \left[\dots \right] i\omega^2 \right] =$$

$$= \Re \left[\exp \left(i \int_0^t \omega(t') dt' \right) \cdot \left(\ddot{\theta}_0 + 2i\omega \dot{\theta}_0 - \omega^2 \theta_0 + i\omega \theta_0 \right) \right]$$

Nell' equazione ora partendo:

$$\Re \left[\underbrace{\exp \left(\dots \right)}_{\ddot{\theta}} \left(\ddot{\theta}_0 + 2i\omega \dot{\theta}_0 - \cancel{\omega^2 \theta_0} + i\omega \theta_0 \right) \right] = \Re \left[\underbrace{-\omega^2 \theta_0 \exp \left(\dots \right)}_{-\omega^2 \theta} \right]$$

$$\cancel{\ddot{\theta}_0 + 2i\omega \dot{\theta}_0 + i\omega \theta_0 = 0}$$

trascurabile

$$\begin{aligned} \frac{d\theta_0}{\theta_0} &= -\frac{1}{2} \frac{d\omega}{\omega} \\ \theta_0(t) &= \theta_0(0) \cdot \sqrt{\frac{\omega(0)}{\omega(t)}} \end{aligned}$$

$$2i\omega \frac{d\theta_0}{dt} = -\cancel{\dot{\theta}_0} \frac{d\omega}{dt}$$

$$\ln \frac{\theta_0(t)}{\theta_0(0)} = \ln \left(\sqrt{\frac{\omega_0}{\omega(t)}} \right)$$

$$\theta_0(t) = \theta_0(0) \sqrt{\frac{w_0}{w(t)}}$$

$$\begin{aligned} \theta(t) &= \operatorname{Re} \left[\theta_0(0) \sqrt{\frac{w_0}{w(t)}} \exp \left[i \int_0^t w(t') dt' \right] \right] = \\ &= \theta_0(0) \sqrt{\frac{w_0}{w(t)}} \cos \left(\int_0^t w(t') dt' \right) \quad \omega \approx w_0 \quad \frac{\omega}{w_0} \approx 1 \end{aligned}$$

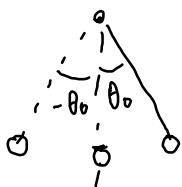
1) Significando di

$$\frac{d^2\theta_0}{dt^2} \ll \omega \frac{d\theta_0}{dt} \quad \frac{d\theta_0}{dt} = -\theta_0 \sqrt{w_0} \quad \frac{1}{2} \frac{1}{w^{3/2}} \frac{dw}{dt}$$

2) Invarianza?

$$\frac{d^2\theta_0}{dt^2} \approx \frac{+\theta_0}{2} \frac{1}{\omega^2} \left(\frac{dw}{dt} \right) + O\left(\frac{d^2w}{dt^2}\right) \approx -\frac{\theta_0}{2} \frac{1}{\omega} \frac{dw}{dt}$$

$$\frac{1}{2} \frac{1}{\omega^2} \left(\frac{d\omega}{dt} \right)^2 \ll \frac{\theta_0}{2} \frac{d\omega}{dt}$$



$$\frac{d\omega}{dt} \ll \omega^2$$

$$\frac{1}{\omega} \frac{d\omega}{dt} \ll \omega$$

$$\frac{d\omega}{dt} \approx \frac{\Delta\omega}{\Delta t}$$

$$\frac{1}{\omega} \frac{\Delta\omega}{\Delta t} \ll \omega \quad \omega \ll \frac{1}{T}$$

$$\frac{\Delta\omega}{\omega} \ll \frac{\Delta t}{T}, \quad T \gg 1$$

Variazione
relativa delle frequenze
frequenza
della oscillazione

$$\text{Se } l = \text{const}$$

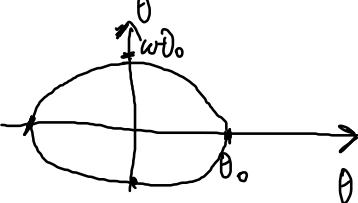
$$\theta(t) = \theta_0 \cos(\omega t)$$

$$\dot{\theta}(t) = -\theta_0 \omega \sin(\omega t)$$

Dunque $\pi \theta_0^2 \omega = \text{cost}$

$$\left(\frac{\theta}{\theta_0} \right)^2 + \left(\frac{\dot{\theta}}{\omega \theta_0} \right)^2 = 1$$

Ellisse nel piano $(\theta, \dot{\theta})$



$$Q_{\text{res}} = \int \overline{\dot{\theta} \frac{d\theta}{dt}} dt =$$

orario
 \circ
 periodo

$$\int_{\text{periodo}} (\ddot{\theta})^2 dt$$

Trivago:

$$\frac{d}{dt} \left(\theta \frac{d\theta}{dt} \right) = (\ddot{\theta})^2 + \theta \frac{d^2\theta}{dt^2}$$

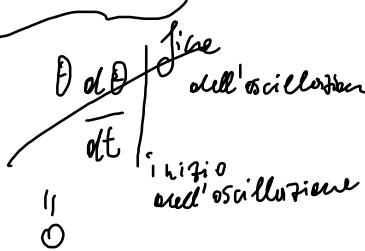
$$\dot{\theta}^2 = \frac{d}{dt} \left(\theta \frac{d\theta}{dt} \right) - \theta \frac{d^2\theta}{dt^2}$$

$\boxed{-\omega^2\theta}$

$$= \int_{\text{periodo}} \frac{d}{dt} \left(\theta \frac{d\theta}{dt} \right) dt + \int_{\text{periodo}} \omega^2 \theta^2 dt$$

periodo

periodo



$$+ \int_0^T \omega^2 \frac{\theta_0^2}{\omega} \cos^2 \left(\int_0^t \omega(t') dt' \right) dt$$

$+ \omega^2 \theta^2$
 Cambio di variabile
 $\int_0^T = \int_0^T \omega(t') dt'$
 $t = 0 \rightarrow t = 0 \int_0^0 \frac{d\theta}{dt} dt' = 0$
 $t = T \rightarrow \int_0^T \frac{d\theta}{dt} dt' = 2\pi$

$$\int \varphi = \int_0^t w(t') dt'$$

$$\frac{d\varphi}{dt} = w(t) \Rightarrow d\varphi = w \frac{dt}{2\pi}$$

$$\theta_{\text{max}} = w_0 \theta_0^2 \int_0^\pi \cos^2(\varphi) d\varphi = \pi w_0 \theta_0^2$$



In un moto adiabatico e periodico nelle coordinate q

si conserva l'Integrale di azione $\int p dq$ periodo $P = \frac{\partial L}{\partial \dot{q}}$

$$\mathcal{L} = \frac{1}{2} m \dot{\underline{v}}^2 + q \underline{A} \cdot \underline{\dot{v}} - q \phi(\underline{x}, t)$$



$$\underline{B} = \underline{\nabla} \times \underline{A}(\underline{x}, t)$$

$$\underline{E}(\underline{x}, t) = -\underline{\nabla} \phi - \partial \underline{A} / \partial t$$

$$m \frac{d \underline{\dot{v}}^2}{dt^2} = q (\underline{\underline{E}} + \underline{\dot{v}} \times \underline{B})$$

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_j} - \frac{\partial \mathcal{L}}{\partial q_j} = 0 \quad q_j \quad j=1 \dots N$$

$$\underline{x}_i \quad \mathcal{L} = \frac{1}{2} m \sum_{j=1}^3 (\dot{x}_j)^2 + q \sum_{j=1}^3 A_j(\underline{x}, t) \dot{x}_j - q \phi(\underline{x}, t)$$

$$q_j \rightarrow x_{-j} q_j^2$$

$$x_j \quad j=1 \dots 3$$

$$\frac{\partial \mathcal{L}}{\partial x_i} = q \sum_{j=1}^3 \frac{\partial A_j}{\partial x_i} \ddot{x}_j - q \frac{\partial \phi}{\partial x_i}$$

Formule per

Derivata di

funzione composta

$$\frac{\partial \mathcal{L}}{\partial \dot{x}_i} = m \ddot{x}_i + q A_i(x, t)$$

3

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{x}_i} = m \ddot{\dot{x}}_i + q \sum_{j=1}^3 \frac{\partial A_j}{\partial x_j} \dot{x}_j + q \frac{\partial A_i}{\partial t}$$