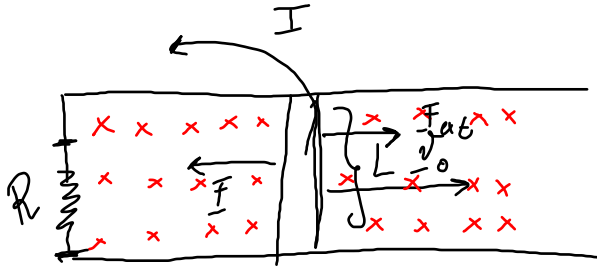
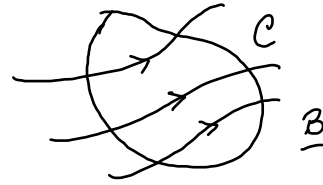


$$f.e.m. = - \frac{d\phi_s(B)}{dt}$$



$$f_{em} = B L v_0 \quad I = \frac{f_{em}}{R} = \frac{B L v_0}{R}$$

Sulla sbarretta agisce la forza  $F = I L \times B$  e frenante

$$Potenza = F \cdot v_0 = \frac{B^2 L^2 v_0^2}{R} = \frac{(f_{em})^2}{R} \rightarrow \text{Potenza dissipata sulla resistenza per effetto Joule}$$

Suppongo, per assurdo, che  $I$  scorra in senso orario



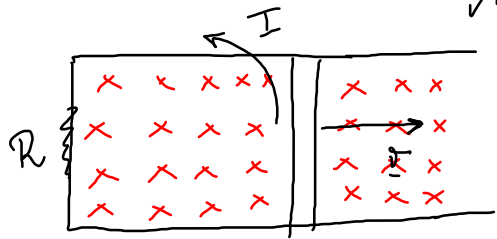
la sbarretta viene accelerata "gratuitamente":  $v$  aumenta  
 forza aumenta ( $\propto v$ )

$$I = \frac{\text{forza}}{R}$$

Conservazione energia  $\Leftarrow$   
 $v$  costante

$$P_R = \frac{(\text{forza})^2}{R} \propto v^2 \text{ aumenta}$$

$v(0) = v_0$  lascio evolvere il sistema



$$\text{forza} = BLv(t)$$

$$I = \frac{\text{forza}}{R} = \frac{BLv(t)}{R}$$

$$\underline{F} = I \underline{L} \times \underline{B}$$

$$|\underline{F}| = \frac{L^2 B^2}{R} v(t)$$

$$F = - \frac{L^2 B^2}{R} v(t)$$

$$\frac{dv}{dt} = - \frac{L^2 B^2}{mR} v$$

$$\gamma = \frac{L^2 B^2}{mR}$$

$$m \frac{dv}{dt}$$

forza di tipo viscoso

$$\frac{dv}{dt} = -\gamma v$$

$$\int_{v_0}^{v(t)} \frac{dv}{v} = -\gamma \int_0^t dt$$

eq. differenziale per  $v(t)$   
a variabili separabili

$$\ln v \Big|_{v_0}^{v(t)}$$

$$= -\gamma t; \quad \ln v(t) - \ln v_0 = -\gamma t$$

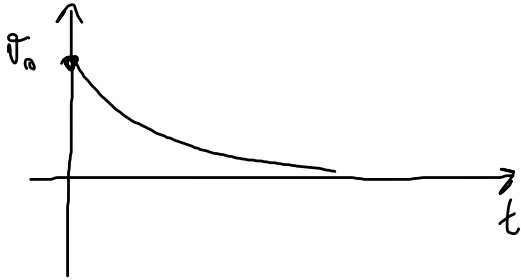
$$\ln \frac{v(t)}{v_0} = -\gamma t; \quad v(t) = v_0 e^{-\gamma t}$$

$$\gamma \stackrel{\text{def}}{=} \frac{1}{\tau}; \quad \tau \stackrel{\text{def}}{=} \frac{1}{\gamma} = \frac{mR}{L^2 B^2}$$

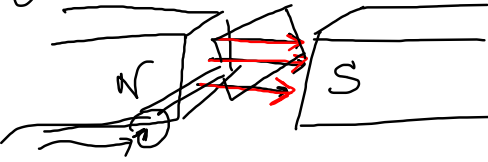
$$\text{Se } t = 5\tau, \text{ allora } \frac{v(5\tau)}{v_0} = e^{-5} \approx 0.7\%$$

$$\tau \propto R, m$$

$$\tau \propto \frac{1}{L^2}, \frac{1}{B^2}$$

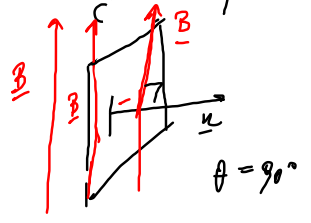
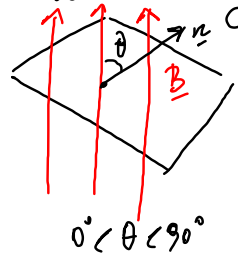
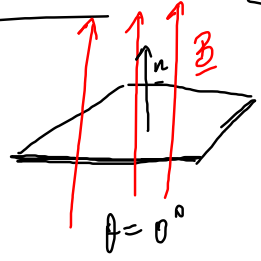


Generatore di tensione alternata



Spira in rotazione con  $\omega = \text{cost}$

Si produce una fem  $\omega$  po la spira



$$\Phi(\underline{B}) = \int \underline{B} \cdot d\underline{S}$$

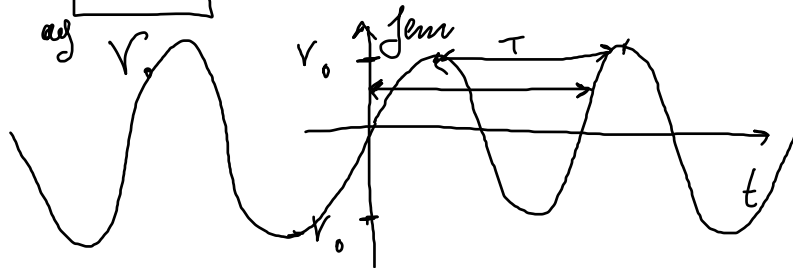
$$\underline{B} \cdot d\underline{S} = B \, dS \, \cos\theta \quad \theta = \omega t$$

$$= B \, dS \, \cos(\omega t)$$

$$fem = - \frac{d\Phi}{dt} = BA_{spira} \omega \sin(\omega t)$$

$$= \int_{spira} B \, dS \, \cos(\omega t) = B \cos(\omega t) \int_{spira} dS = BA_{spira} \cos(\omega t)$$

$$j_{em} = \underbrace{BA_{sp}}_{\text{ag}} \omega \sin(\omega t) = V_0 \sin(\omega t)$$



$$T = \frac{2\pi}{\omega}$$

$$\nu = \frac{1}{T} = \frac{\omega}{2\pi}$$

$$\nu = 50 \text{ Hz}$$

standard EU

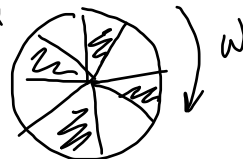
$$\nu = 60 \text{ Hz}$$

USA

$$P = \frac{(j_{em})^2}{R} = \frac{V_0^2}{R} \sin^2(\omega t) \quad \text{Pot. istantanea}$$

$$\langle P \rangle = \frac{\int_0^T \frac{V_0^2}{R} \sin^2(\omega t) dt}{T}$$

$$= \frac{V_0^2}{R} \cdot \frac{\omega}{2\pi} \int_0^{\frac{2\pi}{\omega}} \sin^2(\omega t) dt = \frac{V_0^2}{R} \cdot \frac{\omega}{2\pi} \cdot \frac{1}{\omega} \int_0^{2\pi} \sin^2 y dy$$



$$t=0 \rightarrow y=0$$

$$t = \frac{2\pi}{\omega} \rightarrow y = 2\pi$$

$$y = \omega t \quad dt = \frac{1}{\omega} dy$$

$$\cos(2y) = \cos^2 y - \sin^2 y = \underbrace{1 - \sin^2 y}_{\cos^2 y} - \sin^2 y = 1 - 2\sin^2 y \Rightarrow \sin^2 y = \frac{1 - \cos(2y)}{2}$$

$$\langle P \rangle = \frac{V_0^2}{2\pi R} \int_0^{2\pi} \left( \frac{1}{2} - \frac{\cos(2y)}{2} \right) dy = \frac{V_0^2}{2\pi R} \left[ \frac{1}{2} \cdot 2\pi - \frac{1}{2} \int_0^{2\pi} \cos(2y) dy \right] = \frac{V_0^2}{2\pi R} \cdot \pi = \frac{V_0^2}{2R}$$

$$i_{em} = V_0 \sin(\omega t)$$

$$\langle P \rangle = \frac{V_0^2}{2R} = \frac{1}{2} \cdot P_{max}$$

$$V_{eff} = \frac{V_0}{\sqrt{2}}$$

$$\langle P \rangle = V_{eff}^2 / R$$

$$V_{eff} = 220 \text{ V EU}$$

$$V_{eff} = 120 \text{ V USA}$$

AC motor

