

Università degli Studi di Milano-Bicocca - Laurea Magistrale in Matematica

**Esame di metodi matematici per l'analisi economica – controllo ottimo**

**27 Gennaio 2020**

Cognome: \_\_\_\_\_ nome: \_\_\_\_\_

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1. (6 punti) Using the variational approach solve the problem

$$\begin{cases} \min_u T \\ \ddot{x} = u \\ x(0) = \dot{x}(0) = -1 \\ x(T) = \dot{x}(T) = 0 \\ |u| \leq 1 \end{cases}$$

2. (6 punti) Using the Dynamic Programming solve the problem

$$\begin{cases} \min_u \int_0^2 (x - u) dt + x(2) \\ \dot{x} = 1 + u^2 \\ x(0) = 1 \end{cases}$$

In order to solve BHJ equation, we suggest to find the solution in the family of functions

$$\mathcal{F} = \{V(t, x) = A + Bt + Ct^2 + D \ln(3 - t) + E(3 - t)x, \text{ with } A, B, C, D, E \text{ constants}\}.$$

3. (6 punti) Let us consider the following optimal control problem

$$\begin{cases} J(\mathbf{u}) = \int_{t_0}^{t_1} f(t, \mathbf{x}, \mathbf{u}) dt \\ \dot{\mathbf{x}} = g(t, \mathbf{x}, \mathbf{u}) \\ \mathbf{x}(t_0) = \boldsymbol{\alpha} \\ \max_{\mathbf{u} \in \mathcal{C}} J(\mathbf{u}) \\ \mathcal{C} = \{\mathbf{u} : [t_0, t_1] \rightarrow U \subset \mathbb{R}^k, \mathbf{u} \text{ admissible}\} \end{cases} \quad (1)$$

with  $\boldsymbol{\alpha}$ ,  $t_0$  and  $t_1$  fixed.

- i. With the appropriate and minimal assumptions, give the necessary condition of Pontryagin for the problem (1);
- ii. with the appropriate assumptions, give the sufficient condition of Mangasarian for the problem (1); it is also required the proof.

4. (6 punti) Let us consider the “moonlanding problem”:

$$\begin{cases} \max_{u \in \mathcal{C}} m(T) \\ \dot{h} = v \\ \dot{v} = \frac{u}{m} - g \\ \dot{m} = -ku \\ h(0) = h_0, \quad h(T) = 0 \\ v(0) = v_0, \quad v(T) = 0 \\ m(0) = M + F \\ m(t) \geq 0, \quad h(t) \geq 0 \\ \mathcal{C} = \{u : [0, T] \rightarrow [0, \alpha], \text{ admissible}\} \end{cases}$$

where  $h_0, M, F, g, -v_0, k$  and  $\alpha$  are positive and fixed constants, and the final time  $T$  is free.

- i. Introduce the problem with all the details;
- ii. prove that the optimal solution has at most one switching point.

5. (6 punti) Let us consider the following zero sum differential game

$$\left\{ \begin{array}{l} \text{Player I: } \max_{\mathbf{u}_1} J(\mathbf{u}_1, \mathbf{u}_2), \quad \text{Player II: } \min_{\mathbf{u}_2} J(\mathbf{u}_1, \mathbf{u}_2) \\ J(\mathbf{u}_1, \mathbf{u}_2) = \int_0^T f(t, \mathbf{x}, \mathbf{u}_1, \mathbf{u}_2) dt + \psi(\mathbf{x}(T)) \\ \dot{\mathbf{x}} = g(t, \mathbf{x}, \mathbf{u}_1, \mathbf{u}_2) \\ \mathbf{x}(0) = \alpha \end{array} \right. \quad (2)$$

where  $T$  is positive and fixed,  $U_i$  are the control sets for the players.

- i. Introduce, with all the details, the definitions of lower value function  $V^-$  and upper value function  $V^+$  (in particular provide the definitions of control and nonanticipative strategy). When the problem (2) admits value function  $V$  ?
- ii. Let us consider the game

$$\left\{ \begin{array}{l} \text{Player I: } \max_{u_1} J(u_1, u_2) \quad \text{Player II: } \min_{u_2} J(u_1, u_2) \\ |u_1| \leq 1 \quad |u_2| \leq 1 \\ J(u_1, u_2) = \int_0^\infty \text{sgn}(x) (1 - e^{-|x|}) e^{-t} dt \\ \dot{x} = (u_1 - u_2)^2 \\ x(0) = x_0 \end{array} \right. \quad (3)$$

Prove that it does not admit value function.

- iii. Now consider the problem

$$\left\{ \begin{array}{l} \text{Player I: } \max_{\mathbf{u}_1} J(\mathbf{u}_1, \mathbf{u}_2), \quad \text{Player II: } \min_{\mathbf{u}_2} J(\mathbf{u}_1, \mathbf{u}_2) \\ J(\mathbf{u}_1, \mathbf{u}_2) = \psi(T, \mathbf{x}(T)) \\ \dot{\mathbf{x}} = g(t, \mathbf{x}, \mathbf{u}_1, \mathbf{u}_2) \\ \mathbf{x}(0) = \alpha \\ (T, \mathbf{x}(T)) \in \partial S \end{array} \right. \quad (4)$$

with  $T$  free and the closed target set  $S \subset [0, \infty) \times \mathbb{R}^n$ . Let us assume that the problem admits a value function in  $C^1$  and that the Isaacs condition is satisfied (if is the case, add further necessary assumptions). Give a geometric proof of the Isaacs equation for the problem (4).