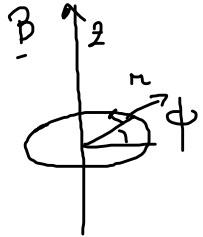


$$S = \oint_{\text{period}} P dq$$

q : periodic coordinate
 $P = \frac{\partial \mathcal{L}}{\partial \dot{q}}$ associated can. mom.



ϕ : gyrophase

$$S = \oint P_{\phi} d\phi$$

$$\mathcal{L} = \frac{1}{2} m \underline{v}^2 + q \underline{v} \cdot \underline{A} - q \varphi = \frac{1}{2} m (\dot{r}_R^2 + \dot{r}_Z^2 + \dot{r}_{\phi}^2) + (v_Z A_Z + v_R A_R + v_{\phi} A_{\phi}) - q \varphi$$

$$\left. \begin{aligned} \underline{B} &= \underline{\nabla} \times \underline{A} \neq 0 \\ \underline{E} &= 0 \Rightarrow \underline{\mathbb{E}} = -\frac{\partial \underline{A}}{\partial t} - \underline{\nabla} \varphi \end{aligned} \right\} \text{set } \varphi = 0$$

$$v_{\phi} = \pi_L \dot{\phi}$$

$$\mathcal{L} = \frac{1}{2} m (\dot{v}_R^2 + \dot{v}_2^2 + r_L^2 \dot{\phi}^2) + q (A_1 \dot{v}_1 + A_2 \dot{v}_2 + A_\phi r_L \dot{\phi})$$

$$\phi \rightarrow \dot{\phi}$$

$$P_\phi = \frac{\partial \mathcal{L}}{\partial \dot{\phi}} = \frac{1}{2} m r_L^2 \cdot 2 \dot{\phi} + q A_\phi r_L = m r_L^2 \dot{\phi} + q A_\phi r_L$$

ϕ comp. ^{canonical} angular momentum

$$S = \int_0^{2\pi} P_\phi d\phi = \int_0^{2\pi} (m r_L^2 \dot{\phi} + q A_\phi r_L) d\phi$$

$$\int_0^{2\pi} m r_L^2 \dot{\phi} d\phi = \int_0^{2\pi} m r_L^2 \frac{d\phi}{dt} \frac{d\phi}{dt} dt = \int_0^{T_L} m r_L^2 (\dot{\phi})^2 dt = \int_0^{T_L} m r_L^2 \frac{v_\phi^2}{r_L^2} dt =$$

adiabatic motion

\downarrow

$$\phi = \frac{v_\phi}{r_L}$$

$$= v_L^2 m \int_0^{T_L} dt = m v_L^2 T_L$$

$$\int_0^{2\pi} g r_L A_\phi d\phi \approx g r_L \int_0^{2\pi} A_\phi d\phi$$

adiabatic motion

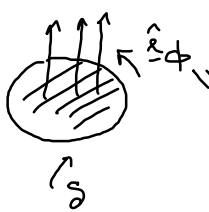
$A_\phi = ?$

Choose a ref. frame : z axis || \underline{B}

$$\underline{B} = \nabla \times \underline{A}$$

$$\int_S \underline{B} \cdot d\underline{S} = \int_S B dS \approx B \cdot \pi r_L^2$$

$$d\underline{l} = r_L d\phi \hat{e}_\phi$$



$$\int_S (\nabla \times \underline{A}) \cdot d\underline{S} = \oint \underline{A} \cdot d\underline{l} = \int_0^{2\pi} (\underbrace{\underline{A} \cdot \hat{e}_\phi}_{A_\phi}) r_L d\phi = \int_0^{2\pi} A_\phi r_L d\phi$$

Stokes theorem Laxmon circle

$$\approx A_\phi r_L \int_0^{2\pi} d\phi = 2\pi A_\phi r_L$$

$$B \pi_L^2 \approx 2\pi A \phi \pi /$$

$$\Rightarrow A \phi = \frac{B \pi_L}{2\pi}$$

$$g \pi_L \int_0^{2\pi} A \phi d\phi = g \pi_L \int_0^{2\pi} \frac{B \pi_L}{2} d\phi \approx g \pi_L^2 \frac{B}{2} \cdot 2\pi$$

$$S = m v_L^2 T_L + g \pi_L^2 B \pi = \frac{m v_L^2}{g B} 2\pi \frac{m}{g B} + g \pi_L^2 B \pi =$$

$$= \frac{m^2 v_L^2}{g B} 2\pi + g \frac{m^2 v_L^2}{g^2 B^2} B \pi = (3\pi) \cdot \frac{m^2 v_L^2}{g B} =$$

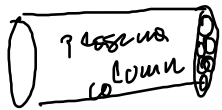
$$= \left(\frac{6\pi m}{g}, \frac{m^2 v_L^2}{2B} \right) = \frac{6\pi m}{g} \cdot \mu$$

If $\Delta t \gg \tau_L$ Δt : time over which a change of \underline{B} occurs

then μ : magnetic moment is an adiabatic invariant

Frozen flux law

$$\Phi(\underline{B}) \text{ Larmor orbit} = B \cdot \pi \cdot r_L^2 = \pi B \frac{m^2 v_L^2}{q^2 B^2} = \frac{2 \cdot m \cdot \pi}{q} \frac{m v_L^2}{2B} = \frac{2 m \pi}{q} \cdot \mu$$



say $B \downarrow$ $\Delta t \gg \tau$ slowly $\Rightarrow \Phi \approx \text{const} : r_L \uparrow \Rightarrow$ plasma column becomes larger

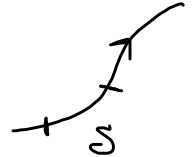
$\Phi = B \pi r_L^2$ say $B \uparrow$ slowly ($\Delta t \gg \tau$) $\Phi \approx \text{const} \rightarrow r_L \downarrow \Rightarrow$ plasma column shrinks

Hydrogen ion $B \approx 1 T$

$$T = \frac{2\pi m}{qB} \approx \frac{6.3 \cdot 1.67 \cdot 10^{-27}}{1.6 \cdot 10^{-19} \cdot 1} \approx \frac{10}{1.6} \cdot \frac{10^{-17}}{10^{-19}} \approx 6 \cdot 10^{-8} \text{ s} \ll \mu\text{s}$$

Plasma confinement in a linear device

$$m \frac{d\vec{v}_\perp}{dt} = q\vec{E}_\perp - i\mu \frac{\partial B}{\partial s} \quad (\text{along } \vec{B})$$



$$\vec{F} = -\mu \nabla |B|$$

