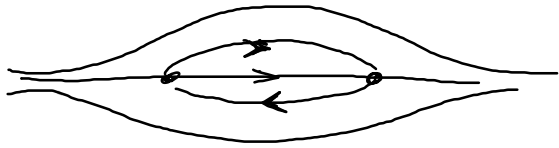


# Mirror machine



Confined particles

Periodic motion

2<sup>nd</sup> adiabatic invariant

S coordinate

$$\underline{P}_\parallel = m\underline{v}_\parallel + q\underline{A}_\parallel \neq m\underline{v}_\parallel$$

$$\oint_{\text{orbit}} \underline{P}_\parallel dS \quad \text{2<sup>nd</sup> adiabatic invariant}$$

When can we assume  $\underline{A}_\parallel = 0$ ?  $(\underline{\nabla} \times \underline{B})_\parallel = \mu_0 \underline{j}_\parallel$   $\underline{j}$ : current density

$$\underline{B} = \underline{\nabla} \times \underline{A}$$

$$[\underline{\nabla} \times (\underline{\nabla} \times \underline{A})]_\parallel = \mu_0 \underline{j}_\parallel$$

$$\nabla \times (\nabla \times \underline{A}) = \nabla (\nabla \cdot \underline{A}) - \nabla^2 \underline{A}$$

~~$$\nabla (\nabla \cdot \underline{A}) - \nabla^2 \underline{A} = \mu_0 \underline{j}_{||}$$~~

$$\nabla^2 A_{||} = -\mu_0 j_{||}$$

Coulomb gauge:  $\nabla \cdot \underline{A} = 0$

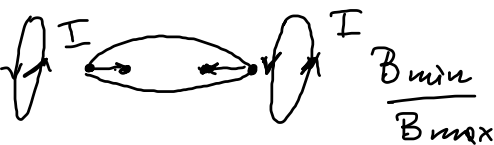
$\oint j_{||} = 0$  (continuity)

$\nabla^2 A_{||} = 0$  satisfied if  $A_{||} = 0$

$$P_{||} = m \dot{\sigma}_{||}$$

$$\mathcal{J} = \int_{\text{closed orbit}} m \dot{\sigma}_{||} ds \sim m \dot{\sigma}_{||} \cdot L$$

closed orbit
orbit size



Say that we increase  $I$  in the coils slowly  
 $V_{\text{eff}} = \mu B \Rightarrow L \downarrow$   
 as slow as possible  
 Thence

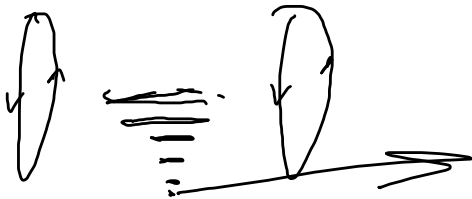
$\Rightarrow v_{\parallel}$   $\uparrow$

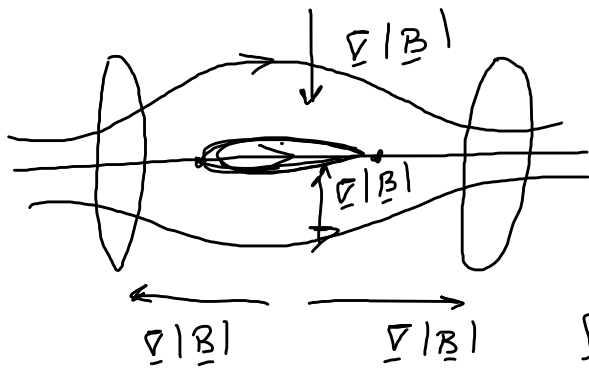
$$\sin \theta = \frac{v_{\perp 0}}{v_0}$$

$\therefore \sin \theta < \sin \theta_c \Rightarrow$  particle is unconfined

$\Rightarrow$  at some point, when  $v_{\parallel}$  is large enough, the particle becomes unconfined.

Fermi acceleration





$\nabla|B| \neq 0$  radially

$$\underline{j} = \frac{-\mu \nabla|B| \times \underline{B}}{qB^2}$$

$$\nabla|B| \propto \hat{e}_r \quad \underline{B} \propto \hat{z}$$

$$\underline{j} \propto -\hat{e}_r \times \hat{z} \propto \hat{e}_\theta$$

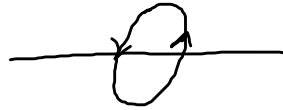
Two types of particles



1st per. motion

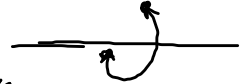


axis encircling



2nd per. motion

3rd per. motion



3<sup>rd</sup> adiabatic invariant

$$\delta \pi_j = \int_0^\tau \underline{v} dt$$

$\tau$ : bounce period

position of the turning point  
after 1 bounce

$$\langle \underline{v} \rangle = \frac{1}{\tau} \delta \pi_j$$

$$\underline{P} = m \langle \underline{v} \rangle + q \underline{A}$$

(canonical momentum)

$$S = \sum_j \int (m \langle \underline{v} \rangle + q \underline{A}) \cdot d\underline{\pi}_j \approx \int (m \langle \underline{v} \rangle + q \underline{A}) \cdot d\underline{\pi}_{\text{bounce}}$$

$j$  = index over the bounces

$$\frac{\int m \langle \underline{v} \rangle \cdot d\underline{\pi}}{\int q \underline{A} \cdot d\underline{\pi}} = \frac{m r_L v_{\perp}}{q \int_{\text{orbit}} \underline{B} \cdot d\underline{S}} \sim \frac{(m r_L v_{\perp})}{(q \pi r_L^2 B)} \sim \frac{r_L^2 \ll 1}{r^2}$$

described by T.P.

$$\oint_{\text{orbit}} \underline{A} \cdot d\underline{l} = \int_S \underline{B} \cdot d\underline{S} = \int_S (\nabla \times \underline{A}) \cdot d\underline{S} = \oint \underline{A} \cdot d\underline{l}$$

Stokes Theorem

$$\oint \underline{A} \cdot d\underline{l} \sim \int q \underline{A} \cdot d\underline{\pi} \propto \phi(\underline{B})_{\text{orbit}}$$

$$\sigma_{\text{drift}} \sim \frac{-\mu \underline{B} \cdot \underline{B}}{q B^2} = -\frac{\mu}{r q} = -\frac{m v_{\perp}^2}{q B r} \rightarrow r_L \cdot \frac{v_{\perp}}{r}$$

$$r_L = \frac{m v_{\perp}}{q B}$$

$$\int m v_{\perp} d\underline{\pi} \sim m v_{\text{drift}} \cdot r \sim m r_L v_{\perp}$$

# 3 adiabatic invariants

Periodic motions

dominant motion

adiabatic invariants

$\mu$

Time scales

$T_L$

$\ll$

Motion between the T.P.

$$S_2 \approx \int_{\text{orbit between T.P.}} v_{||} ds$$

$T_{\text{bounce}}$

Motion of the T.P. around the axis

$$S_3 \approx \oint_{\text{T.P. orbit}} \phi(B)$$

$\ll$

$T_{\text{T.P.}}$