

$$V_{eff} = \mu B$$

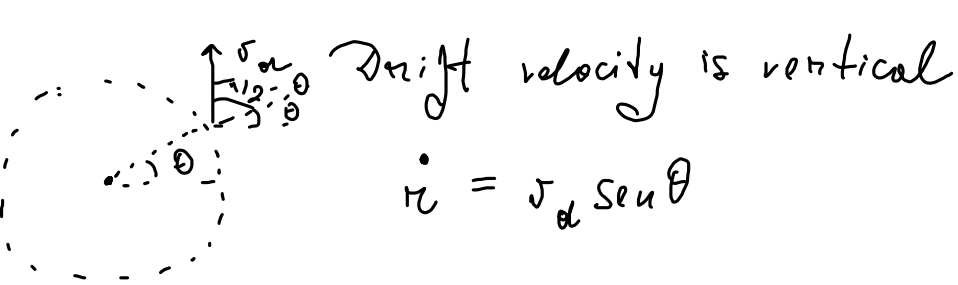
$$B = \frac{B_0 R_0}{R}$$

R_0 : machine radius

$$\frac{v_{in}}{v_{1.0}} \lesssim \sqrt{2E}$$

$$R = R_0 + r \cos \theta \quad \epsilon = \frac{r}{R_0}$$

$$B = \frac{B_0 R_0}{R_0 + r \cos \theta} = \frac{B_0}{1 + \epsilon \cos \theta} \approx B_0 (1 - \epsilon \cos \theta)$$



$$\dot{r} = v_d \sin \theta$$

$$v_d = v_{d \text{ centrif}} + v_{d \nabla |B|} \approx v_{d \nabla |B|}$$

$$\frac{v_{||}}{v_{\perp}} \ll \sqrt{2} \epsilon \Rightarrow v_{||} \ll v_{\perp}$$

$$v_{d \nabla |B|} \approx \frac{\mu \nabla |B| \cdot B}{q B^2} \approx \frac{\mu B^2 / R}{q B^2}$$

$$\approx \frac{m v_{\perp}^2}{2 B R q}$$

$$\dot{r} \approx \frac{m v_{\perp}^2}{2 B R q} \sin \theta$$

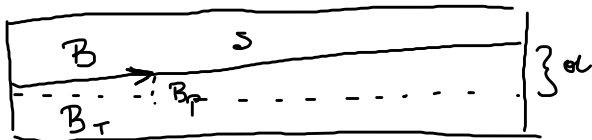
$$\dot{j}_{\parallel} = ?$$

$$\text{in } \dot{j}_{\parallel} = -\mu \frac{\partial B}{\partial s} = -\mu \frac{\partial B}{\partial \theta} \cdot \frac{\partial \theta}{\partial s}$$

s : coordinate along the field line

$$B = B_0 (1 - \epsilon \cos \theta) \quad \frac{\partial B}{\partial \theta} = B_0 \epsilon \sin \theta$$

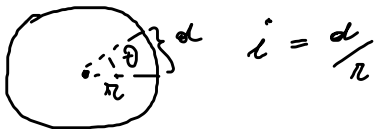
Cylindrical approx



$$\frac{d}{s} = \frac{B_r}{B}; \quad d = \frac{B_r}{B} \cdot s$$

$$\theta = \frac{d}{r} = \frac{B_r \cdot s}{B} \cdot \frac{1}{r}$$

$$\frac{\partial \theta}{\partial s} = \frac{B_r}{\pi B}$$



$$\dot{v}_{\parallel} \approx -\frac{1}{m} \mu \frac{\partial B}{\partial \theta} \frac{\partial \theta}{\partial s} = -\frac{1}{m} \cancel{\mu} \cancel{v_{\perp}^2} \cancel{B_0} \epsilon \sin \theta \frac{B_p}{\cancel{\mu B}} \rightarrow \frac{v_{\perp}^2}{R_0}$$

$$B \approx B_0$$

$$\frac{dv_{\parallel}}{dt} \approx -\frac{v_{\perp}^2 B_p \sin \theta}{2RB} \quad (1)$$

$$\dot{\pi} = \frac{d\pi}{dt} \approx \frac{m v_{\perp}^2 \sin \theta}{2RBq} \quad (2)$$

$$\frac{(1)}{(2)} \quad v_{\parallel} ? \pi$$

$$\frac{dv_{\parallel}}{d\pi} \approx -\frac{v_{\perp}^2 B_p \sin \theta}{2RB} \cdot \frac{2RBq}{m v_{\perp}^2 \sin \theta} \approx -\frac{B_p q}{m}$$

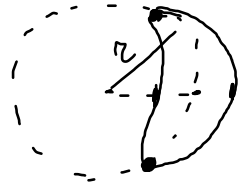
$$\int_{v_{\parallel}=0}^{\circ} dv_{\parallel} \approx -\frac{q B_p}{m} \int_{\pi}^{\pi_{tr}} d\pi ; \quad 0 - v_{\parallel} = -\frac{q B_p}{m} (\pi_{tr} - \pi)$$

$$v_{\parallel} \approx \frac{qB_p}{m} (r_{TP} - r);$$

$$r \approx -\frac{m}{qB_p} v_{\parallel} + r_{TP}$$

$$\Delta = \frac{m v_{\parallel}}{qB_p}$$

$$v_{\parallel} = 0 \Rightarrow r = r_{TP}$$



Displacement Δ is maximum when v_{\parallel} is maximum

$$\Delta_{\text{trapp}} = \frac{m v_{\parallel}}{qB_p} \approx \frac{m \sqrt{2E} v_{\perp 0}}{qB_p} \approx r_{L,p} \cdot \sqrt{2E} \quad \begin{matrix} E \ll 1 \\ \sqrt{E} > E \end{matrix}$$

↑
at most

$$\frac{v_{\perp 0}}{v_{\perp 0}} < \sqrt{2E}$$

$$\Delta_{\text{trapp}} > \Delta_{\text{passing}}$$

$$\Delta_{\text{passing}} \approx E \cdot r_{L,p}$$